## **ROS2 from dev to deploy**

#### on nvidia jetson

## Agenda

- Dev
- Build and test
- Deploy
- Source control (??)
- Version control



robobe

#### Today

- Dev on linux machine as python project (no ROS)
- Deploy: copy python files to remote system
   Deploy as ZIP
- Deploy: Burn pre cocked jetson image

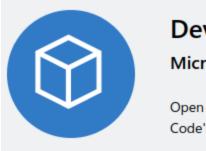
## **Docker as a way of life**

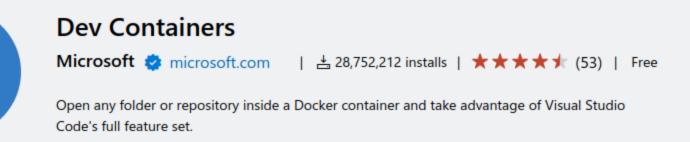
- Dev: using vscode devcontainer
- Build: using docker to build for different architecture
- Test: using docker as test environment (allow clean system)
- Deploy: Deploy the application as cocked docker image



#### Dev

- Using VSCode devcontainer
  - support remote development (run on jetson)
- Docker hierarchy
  - OS with Chosen ROS version + simulator + common dev tools
  - Project runtime dependencies (runtime/test)
  - Project dev dependencies (dev)
  - Project cycle (forget package and python pip)





## Build

- Cross Compiler
- Using docker as cross compiler environment
  - using dev docker that build for the jetson arm architecture



#### Test

 Using docker as consistent and repetitive environment for testing

 Use it to test package install tests



# Deploy - Find your way

- deb packages
- docker image
- jetson image



## Deploy - debian package

- Standard
- The linux/debian way
- every package are installable has version and metadata
- easy to deploy from remote



## **Deploy - jetson image**

- pre install jetson image with all project dependencies and code
- Code install as debian package
- easy to copy

## **Deploy - with docker**

- Build application docker with all dependencies
- Easy deploy

## **Deploy - with docker - when**

- legacy
- test's
- mixing system
- when is no other way

## **Deploy - with docker - why not**

- Hardware issue
- Hard to deploy from remote

## Version

- Every thing has a version
  - package
  - $\circ~\text{OS}$  image
  - $\circ$  docker image
- Every project / application has version page

#### **Control after release**

- Dev days: yes, we know ourself
- From release and on:
  - Source control
  - $\circ~$  Ticket and issue
  - $\circ\,$  Code review and test



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## All fit together

- Build Debian packages
- Install Packages on the docker image
- Backup jetson image with docker include

## **Final thought**

- $\bigcirc$  Docker for dev using devcontainer
- Ocker for build
- Ocker for test
- Ocker for production